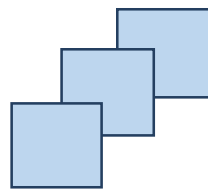


FIFOTRACK COMMAND LIST




Model: A100

Version: V1.3

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Document History

| Version | Revision Date | Author | Detail |
|---------|---------------|---------|--|
| V1.3 | Sep 27, 2019 | Vito Hu | Modify <u>B04</u> , <u>B08</u> , <u>B34</u> , <u>B96</u> commands Delete <u>B15</u> command Delete <u>Enter Sleep</u> , <u>Wake Up</u> alarm code |
| V1.2 | Dec 12, 2018 | Vito Hu | Add <u>B29</u> , <u>B34</u> , <u>B80</u> , <u>B81</u> , <u>B82</u> , <u>B96</u> , <u>B99</u> , <u>C06</u> , <u>C08</u> Delete <u>D01</u> , <u>D02</u> , <u>D03</u> , <u>D04</u> and <u>Appendix B</u> |
| V1.1 | Sep 10, 2015 | Cici Wu | Initial Version |

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1 GPRS Command Format

GPRS uplink (i.e.: Data is sent from terminal to platform) command format:

\$\$<pack-len>,<ID>,<work-no>,<cmd-code>,<cmd-para>*<checksum>\r\n

GPRS downlink (i.e.: Data is sent form platform to terminal) command format:

##<pack-len>,<ID>,<work-no>,<cmd-code>,<cmd-para>*<checksum>\r\n

Remarks:

- ⦿ Comma (,) is used to separate data field, and it is necessary. There is no space before or after comma.
- ⦿ pack-len: Package Length, decimal string format, the field of *pack-len* is {,<ID>,<work-no>,<cmd-code>,<cmd-para>}, be careful, comma(,) in front of *ID* included.
- ⦿ ID: Terminal ID, default IMEI.
- ⦿ work-no: working number, hexadecimal string format, cyclic accumulation from 1 to 0xFFFF.
- ⦿ cmd-code: Command code, or specification of data type.
- ⦿ cmd-para: parameter or description of *cmd-code*, which is described in the following chapter.
- ⦿ checksum: checksum of package, 2 bytes hexadecimal string format, XOR of {<pack-len>,<ID>,<work-no>,<cmd-code>,<cmd-para>}
- ⦿ \r\n: End of package, i.e. <CR><LF>.
- ⦿ Without specification, multi-byte binary data in *cmd-para* uses big endian format, i.e. Most Significant Byte first.

2 SMS Command Format

Sending SMS (from mobile to tracker) command format:

<password>,<cmd-code>,<cmd-para>

Reply SMS (from tracker to mobile) data format:

<cmd-code>,<proc-result>

01 password: SMS password, 6 digits, default "000000".

02 cmd-code: command code, the same as cmd-code filed in GPRS command.

03 cmd-para: command parameter, the same as cmd-para filed in GPRS command.

04 proc-result: command process result

OK – Succeed.

05 SMS command with invalid password, or with incorrect format, no reply will be sent.

3 Serial port (COM) Command Format

Setting command format:

#<cmd-code>,<cmd-para><CR><LF>

Reply data format:

#<cmd-code>,<proc-result><CR><LF>

cmd-code, cmd-para: the same as corresponding filed of GPRS/SMS command.

proc-result: SMS command procession result

OK – Succeed.

UNSUPPORT – Command not supported.

FAILED –Procession failed.

4 Command Writing Specification

- ⦿ Comma (,) is used to separate multi-filed, there is no space before and after comma.
- ⦿ For command with multi parameters, filed(s) can be empty, the corresponding parameter is set to default.
- ⦿ The following chapters describe cmd-code and cmd-para.
- ⦿ The “Retrieve” row in the following chapters describes the corresponding query command.

5 Command List

| B00 – Setting GPRS Parameters | |
|--------------------------------------|---|
| Source | GPRS/COM/SMS |
| Description | <p>B00,<svr_type>,<net_addr>,<net_port></p> <p>01 svr_type: server selection, 1--main server, 2--backup server; When the connection to main server cannot be reached, tracker will automatically connect to the backup server. This avoids data losses.</p> <p>02 net_addr: server IP or domain.</p> <p>03 net_port: server port.</p> |
| Reply | <p>B00,<err_code></p> <p>01 err_code: procession error code.</p> <p style="padding-left: 40px;">OK – Succeed.</p> <p style="padding-left: 40px;">UNSUPPORT – Command not supported.</p> <p style="padding-left: 40px;">FAILED – Procession failed.</p> |
| Example | <p>B00,1, 47.88.35.165,10502</p> <p>01 Set main server: IP-47.88.35.165, port-10502.</p> |
| Retrieve | <p>C04,B00,<svr_type></p> <p>01 svr_type: server selection, the same as <u>svr_type</u> field in setting command.</p> |

| B01 – Setting GPRS APN Parameters | |
|--|--|
| Source | GPRS/COM/SMS |
| Description | <p>B01,<apn_name>,<apn_usr>,<apn_pwd></p> <p>01 apn_name: APN name.</p> <p>02 apn_usr: APN user name.</p> <p>03 apn_pwd: APN password.</p> <p>04 Leave <u>apn_usr</u>, <u>apn_pwd</u> field empty, if no APN username and APN password exist.</p> <p>05 Contact to local ISP for APN detail.</p> |
| Reply | <p>B01,<err_code></p> <p>01 err_code: procession error code.</p> <p style="padding-left: 40px;">OK – Succeed.</p> <p style="padding-left: 40px;">UNSUPPORT – Command not supported.</p> <p style="padding-left: 40px;">FAILED – Procession failed.</p> |
| Example | <p>B01,cmnet</p> <p>01 Set APN name to “cmnet”, APN login username and password empty.</p> |
| Retrieve | C04,B01 |

| B02 – Setting GPRS Link Protocol | |
|---|---|
| Source | GPRS/COM/SMS |
| Description | B02,<link_type> 01 link_type: Link protocol, value TCP or UDP. 02 default TCP protocol. |
| Reply | B02,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B02,TCP 01 Set link protocol to TCP. |
| Retrieve | C04,B02 |

| B03 – Setting Tracking Time Interval | |
|---|---|
| Source | GPRS/COM/SMS |
| Description | B03,<basic_tmr>,<accoff_tmr>,<parking_tmr> 01 basic_tme: normal time interval, unit s. 02 accoff_tmr: time interval when ACC OFF, unit s, default 0s. 03 parking_tmr: time interval when parking, unit s, default 0s. 04 When ACC is connected, tracker uses <u>accoff tmr</u> priority, <u>parking tmr</u> is ignored. |
| Reply | B03,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B03,30 01 Set timing tracking interval to 30s, tracker uploads position data every 30s. |
| Retrieve | C04,B03 |

| B04 – Setting Roaming Tracking Time Interval | |
|---|---|
| Source | GPRS/COM/SMS |
| Description | B04, <roam_basic_tmr>,<roam_accoff_tmr>,<roam_parking_tmr> 01 roam_basic_tmr: roaming time interval, unit s, default 0s. 02 roam_accoff_tmr: time interval when ACC OFF under roaming, unit s, default 0s. 03 roam_parking_tmr: time interval when parking under roaming, unit s, default 0s. 04 When both <u>roam accoff tmr</u> and <u>roam parking tmr</u> are set, <u>roam parking tmr</u> will be ignored in actual usage. 02 When both <u>B03</u> and <u>B04</u> (<u>roam basic tmr</u> != 0) are set, tracker uses below logic for |

| | |
|----------|---|
| | uploading: <ul style="list-style-type: none"> ⊙ When roaming detected, tracker uploads GPRS using <u>B04</u> setting, according to ACC, moving/parking status ⊙ For non-roaming condition, tracker uploads GPRS using <u>B03</u> setting, according to ACC, moving/parking status |
| Reply | B04,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B04,3600 01 Set timing tracking interval to 3600s while roaming. B04,3600,7200 01 Setting timing tracking interval to 3600s when ACC ON, 7200s when ACC off, under roaming status |
| Retrieve | C04,B04 |

B05 – Setting Distance Tracking Interval

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B05,<basic_dst> 01 basic_dst: Distance tracking interval, unit meter. 02 Distance Tracking is independent from timing tracking. |
| Reply | B05,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B05,100 01 Set distance tracking to 100m. |
| Retrieve | C04,B05 |

B07 – Setting the Direction Change Upload

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | B07,<course> 01 course: direction change angle, unit degree, range 1--359, default 0. 02 When <u>course</u> is set to 0, direction change upload is disabled. 03 When driving direction change exceeds the setting value, tracker will upload a position data for supplement. |
| Reply | B07,<err_code> |

| | |
|----------|---|
| | 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B07,30 01 Set direction change angle to 30°. |
| Retrieve | C04,B07 |

B08 – Setting Speeding Alarm

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | B08,<speeding>,<buz> 01 speeding: speed, unit km/h, range 0--300, default 0. 02 When <i>speeding</i> is set to 0, speeding alarm is disabled. 03 buz: 1—Enable buzzer when speeding; 0—Disable(default) 04 When <i>buz==1</i> , tracker controls buzzer via OUT2, till speed returns to normal |
| Reply | B08,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B08,90 01 Set speed limit to 90km/h; Disable buzzer |
| Retrieve | C04,B08 |

B10 – Setting SMS Password

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B10,<sms_pwd> 01 sms_pwd: SMS password, 6 digits, default “000000”. |
| Reply | B10,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B10,472627 01 Set SMS password to “472627”. B10,47262A 01 Invalid command, because SMS password needs to be a 6 digits string. |
| Retrieve | C04,B10 |

B11 – Setting SOS Number

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B11,<sos_num1>,<sos_num2>,<sos_num3> 01 sos_num1, 2, 3: SOS numbers to be set; 3 numbers can be set at most. 02 Refer to B23 for the function of SOS number(s). |
| Reply | B11,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B11,15698210011,,15698210200 01 Set sos_num1 to 15698210011, sos_num2 to empty, sos_num3 to 15698210200. |
| Retrieve | C04,B11 |

B12 – Output Control

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | B12,<index>,<action>,<safe_speed> 01 index: out port selection, value 1, 2, 3... etc.. 02 action: Output control, 0--output low level, 1--output high level. 03 safe_speed: speed limit, unit km/h, range 1--300; when this parameter is set to 0, or this field is empty, output control takes effect immediately; Other value, set the speed limit for output control. When the driving speed is lower than the speed limit, the output control takes effect. |
| Reply | B12,<err_code> 01 err_code: error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED –Processing failed. |
| Example | B12,1,1,20 01 Set OUT1 to output high level when speed less than 20km/h. |
| Retrieve | UNSUPPORT |

B13 – Pulse Output Control

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | B13,<index>,<on_time>,<off_time>,<pls_cnt> 01 index: out port specification, value 1, 2, 3... etc.. 02 on_time: Duration of high level, unit ms. 03 off_time: Duration of low level, unit ms. |

| | |
|----------|---|
| | 04 pls_cnt: Pulse number. |
| Reply | B13,<err_code> 01 err_code: error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED –Processing failed. |
| Example | B13,1,1000,1000,10 01 Set OUT1 to output 10 pulse, whose high level duration 1000ms, low level duration 1000ms. |
| Retrieve | UNSUPPORT |

B14 – Setting SMS Time Zone

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | B14,<tzone> 01 tzone: time zone, range [-12, 12]. 02 Default value of <i>tzone</i> is 0. 03 When SMS time zone is set, all tracking/alarm SMS use <i>tzone</i> for date & time. 04 GPRS data uploading uses UTC-0 time zone. |
| Reply | B14,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B14,-8 |
| Retrieve | C04,B14 |

B16 – Setting Initial Mileage and Initial Runtime

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B16,<init_mile>,<init_runtime> 01 init_mile: initial mileage, unit meter, default 0m. 02 init_runtime: initial runtime, unit s, default 0s. |
| Reply | B16,<err_code> 01 err_code: error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED –Processing failed. |
| Example | B16 01 Set both initial mileage and runtime to 0 |
| Retrieve | C04,B16 01 The retrieved value is current mileage and current runtime, not the setting ones. |

| B17 – Clear Blind Data | |
|-------------------------------|---|
| Source | GPRS/COM/SMS |
| Description | B17,<data_type> 01 data_type: blind data type. 1 – GPRS Blind. 2 – SMS blind. 3 – Both GPRS and SMS blind. |
| Reply | B17,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B17,3 01 Clear both GPRS and SMS blind data. |
| Retrieve | UNSUPPORT |

| B18 – Setting in-port Working Mode | |
|---|---|
| Source | GPRS/COM/SMS |
| Description | B18,<input>,<valid_mode> 01 input: in-port selection, 1--input1, 2--input2, etc.. 02 valid_mode: valid trigger mode, 0--low level valid, 1--high level valid. |
| Reply | B18,<err_code> 01 err_code: error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED –Processing failed. |
| Example | B18,3,1 01 Set IN3 to high level valid mode. |
| Retrieve | C04,B18,<input> 01 input: in-port selection, the same as <u>input</u> field in setting command. |

| B19 – Setting Circle geo-fence | |
|---------------------------------------|--|
| Source | GPRS/COM/SMS |
| Description | B19,<index>,<flag>,<radius>,<lat>,<lon> 01 index: fence index, value 1~8, i.e.: 8 geo-fence can be set at most. 02 flag: alarm flag flag=1: Trigger alarm when exit fence. flag=2: Trigger alarm when enter fence. |

| | |
|----------|---|
| | <p>flag=3: Trigger alarm both enter and exit fence.</p> <p>03 radius: radius of circle geo-fence, unit meter.</p> <p>04 lat: latitude of center point, decimal string format.</p> <p>05 lon: longitude of center point, decimal string format.</p> <p>06 When <u>lat</u> and <u>lon</u> are empty, current latitude and longitude is used, while GPS valid signal is needed.</p> <p>07 When <u>flag</u>, <u>radius</u>, <u>lat</u>, <u>lon</u> are empty, delete geo-fence specified by <u>index</u>; When <u>index</u>=0 or empty, delete all.</p> |
| Reply | <p>B19,<err_code></p> <p>01 err_code: procession error code.</p> <p>OK – Succeed.</p> <p>UNSUPPORT – Command not supported.</p> <p>FAILED – Procession failed.</p> |
| Example | <p>B19,1,3,200</p> <p>01 Set the first circle geo-fence, centre point: current location, radius: 200m, output alarm both enter and exit fence.</p> |
| Retrieve | <p>C04,B19,<index></p> <p>01 index: fence index, value 1~8, the same as <u>index</u> field in setting command.</p> |

B21 – Setting Fatigue Driving

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | <p>B21,<drowsy_time>,<rest_time></p> <p>01 drowsy_time: Fatigue driving time, unit s, default 14400s.</p> <p>02 rest_time: Minimum rest time after fatigue driving, unit s, default 1200s.</p> <p>03 When <u>drowsy time</u> is set to 0, fatigue driving alarm is disabled.</p> <p>04 The field <u>rest time</u> can be empty, while the default value is used.</p> <p>05 When <u>drowsy time</u> and <u>rest time</u> are empty, both values are set to default.</p> |
| Reply | <p>B21,<err_code></p> <p>01 err_code: procession error code.</p> <p>OK – Succeed.</p> <p>UNSUPPORT – Command not supported.</p> <p>FAILED – Procession failed.</p> |
| Example | <p>B21</p> <p>01 Set fatigue driving time to the default value 14400s, and minimum rest time to the default value 1200s.</p> |
| Retrieve | C04,B21 |

B22 – Setting Maximum Parking Time

| | |
|-------------|--------------|
| Source | GPRS/COM/SMS |
| Description | B22,<time> |

| | |
|----------|---|
| | 01 time: Maximum parking time, unit s, default 0s, i.e. parking overtime alarm is disabled. 02 When parking time exceeds preset value, a parking overtime alarm triggered. |
| Reply | B22,<err_code> 01 err_code: error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED –Processing failed. |
| Example | B22,1200 01 Set maximum parking time to 1200s. |
| Retrieve | C04,B22 |

B23 – Setting Alarm Action

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B23,<alm-code>,<GPRS><SMS><two-way-call><monitor-call><photo><AN-idx> 01 alm-code: Alarm type, refer to Appendix –A . 02 GPRS: Disable/enable GPRS uploading. 03 SMS: Disable/enable SMS to SOS number. 04 two-way-call: Disable/enable SOS number dialing under two-way conversation. 05 monitor-call: Disable/enable SOS number dialing under monitor mode. 06 photo: Disable/enable photographing. For A100, photographing is not supported. 07 AN-idx: Complicated action, value 1~6, which corresponds to index field in B24 command; AN is composed of a serial command sets, performing user define operations; Refer to B24 command for detail. 08 When both two-way-call and monitor-call are set, monitor-call is valid, while two-way-call ignored. 09 two-way-call or monitor-call is valid when SOS number set, refer to B11 command for SOS number(s) setting. |
| Reply | B23,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B23,2,110102 01 Set action when SOS triggered: a Sending GPRS alarm data to platform. b Sending alarm SMS with C01 format to SOS number. c Dial SOS numbers under monitor mode. d Perform operations which is defined by B24 |
| Retrieve | C04,B23,<alm-code> 01 alm-code: Alarm type, refer to Appendix –A . The same as alm-code field in setting command. |

B24 – Setting Complicated Alarm Action

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | <p>B24,<AN-idx>,'#oper-1',<delay_t>,'#oper-2',....</p> <p>01 The command defines complicated alarm action, “AN” for short; AN is used associated with <u>B23</u> setting. When both “<u>AN-idx</u>” field in <u>B23</u> command, and AN detail in <u>B24</u> are set, operation can be performed then.</p> <p>02 AN-idx: AN index, value 1~6, corresponds to 1~6 operation sets; It can be selected by <u>AN-idx</u> field in <u>B23</u> command.</p> <p>03 #oper-[1,2...]: Operation instruction, composed of a serial command(s). Maximum length of 64 bytes.</p> <p>04 delay_t: Delay time between adjoining operation, unit second. It means, tracker performs operations defined by <u>opera-1</u>, delay <u>delay_t</u> seconds, then perform <u>opera-2</u></p> <p>05 The writing rule of <u>B24</u>:</p> <ul style="list-style-type: none"> a Single quotes in front of and behind <u>oper-x</u> are needed, which is used to define operation start b <u>oper-x</u> is composed of commands sets, it is written in “SMS Command Format”. For example, '#B12,1,1' c <u>delay_t</u> is written in digital directly, there is no single quote in front or behind <p>06 The operation flow of AN action</p> <ul style="list-style-type: none"> a Tracker detects alarm occurring. b Tracker checks whether <u>AN-idx</u> is selected in <u>B23</u>, and whether AN detail is set in <u>B24</u>. c When both <u>B23</u> and <u>B24</u> is set, tracker performs operation defined by <u>B24</u>. |
| Reply | <p>B24,<err_code></p> <p>01 err_code: procession error code.</p> <ul style="list-style-type: none"> OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | <p>B23,2,100003</p> <p>B24,3,'#B12,1,1',3,'#B12,1,0'</p> <p>01 Tracker will upload GPRS package, and perform AN3 when SOS detected.</p> <p>02 When SOS detected, tracker uploads GPRS alarm package, set OUT1 high level, delay 3s, and then set OUT1 low level.</p> |
| Retrieve | <p>C04,B24,< AN-idx ></p> <p>01 AN-idx: AN index, the same as <u>AN-idx</u> field in setting command</p> |

B26 – Setting Alarm SMS Head String

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | <p>B26,<alm-code>,<sms_string></p> <p>01 alm-code: Alarm type, refer to <u>Appendix –A</u>.</p> |

| | |
|----------|--|
| | 02 sms_string: SMS head string, 16 bytes length at most. 03 Refer to Appendix-A for default string. |
| Reply | B26,<err_code> 01 err_code: error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED –Processing failed. |
| Example | B26,2,HELP 01 Set SMS head string of SOS to “HELP”. |
| Retrieve | C04,B26,<alm-code> 01 alm-code: Alarm type, refer to Appendix –A . The same as alm-code field in setting command. |

B27 – Setting Parameters of Harsh Acceleration Alarm

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | B27,<speed_var>,<time_lmt> 01 speed_var: maximum acceleration speed, unit km/h, default 0. 02 time_lmt: hard acceleration detection time, unit s, default 0. 03 Refer to Appendix –A for alm-code of harsh accelerate |
| Reply | B27,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B27,40,2 01 Set hard acceleration parameters: 40km/h speed variation within 2s. |
| Retrieve | C04,B27 |

B28 – Setting Parameters of Harsh Braking Alarm

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | B28,<speed_var>,<time_lmt> 01 speed_var: maximum decrease speed, unit km/h, default 0. 02 time_lmt: hard braking detection time, unit s, default 0. 03 When driving speed decrease beyond speed var , tracker triggers hard braking alarm. 04 Refer to Appendix –A for alm-code of harsh brake |
| Reply | B28,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |

| | |
|----------|---|
| Example | Refer to example in B27 |
| Retrieve | C04,B28 |

B29 – Setting Sensitivity of Motion Sensor

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B29,<level> 01 level: sensitivity of motion sensor, value [0, 10]; the smaller value, the higher sensitivity |
| Reply | B29,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B29,5 |
| Retrieve | C04,B29 |

B31 – Setting SOS Number Attribute

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B31,<sos-num>,<two-way-call>,<monitor>,<pos-sms> 01 Set SOS number attribute, refer to B11 command for SOS number setting. 02 sos-num: SOS index, value 1, 2, 3, which corresponds to SOS number set by B11 command. 03 two-way-call: attribute of two-way conversation. 04 monitor: attribute of monitor-mode conversation. 05 pos-sms: attribute of position SMS. 06 Description of attribute: two-way-call: tracker picks up incoming phone-call in two-way conversation mode. monitor: tracker picks up incoming phone-call in monitor mode. pos-sms: Tracker sends position SMS after incoming phone-call ends. Refer to C01 command for SMS format. 07 When both two-way-call and monitor are set, monitor is valid, i.e.: tracker picks up phone-call in monitor mode. 08 When the command string has only sos-num field, default attribute is set to corresponding SOS number. 09 Default attribute of SOS number: two-way-call and pos-sms . |
| Reply | B31,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. |



| | |
|----------|---|
| | FAILED – Procession failed. |
| Example | B31,1,1,1,1 01 Set attribute of the first SOS number: tracker automatically picks up incoming phone-call under monitor mode, reply a position SMS. |
| Retrieve | C04,B31,<sos-num> 01 sos-num: SOS index, value 1, 2, 3. The same as <u>sos-num</u> field in setting command. |

B33 – Setting Maximum Idle Time

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B33,<idle_time> 01 idle_time: maximum idle time, unit: s, default 0s. This parameter should be greater than 120s. 02 idle definition: ACC ON, but no speed, which means engine running under idle mode. 03 When idle mode detected, tracker starts idle time counter, and triggers <u>Idling Alarm</u> (<u>alm_code</u> =35), if counter exceeds <u>idle time</u> . |
| Reply | B33,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B33,600 01 Set maximum idle time to 600s |
| Retrieve | C04,B33 |

B34 – Setting Voltage Range for AD Port

| | | | | | |
|-------------|---|-------------------|-------------------|----------------------|--|
| Source | GPRS/COM/SMS | | | | |
| Description | B34,<index>,<min_volt>,<max_volt>,<filter-option> 01 index: AD port index, value 1, which corresponds to AD1 02 min_volt: AD port voltage when external input is 0%, unit V 03 max_volt: AD port voltage when external input is 100%, unit V 04 filter-option: filter option for AD sample data <u>filter-option</u> ==0 (default): When external power exists, sample AD data and upload real-time; When external power disconnected, keeping the last sample value, and upload to server <u>filter-option</u> ==2: upload AD sample data real-time, ignoring ACC and external power status 05 Default value for AD input | | | | |
| | port | min_volt/V | max_volt/V | filter-option | Description |
| | AD1 | 0 | 5 | 0 | Get sample data according to external power status |

| | |
|----------|---|
| Reply | B34,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B34,1,0,5.0 01 Setting voltage range of AD1 to [0,5]V, getting sample data when external power exist, keeping sample data when external power disconnected |
| Retrieve | C04,B34,<index> |

B80 – Setting Fuel Theft/Filling Alarm

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B80,<ad-idx>,<theft-percentage>,<filling -percentage>,<use-acc> 01 The command is used for AD fuel sensor, such as AS10; Besides, it is valid on regular tank only at present. 02 ad-idx: AD channel which connects to fuel sensor, value 1/2; If <u>ad-idx==0</u> , disable fuel theft/filling function. 03 theft-percentage: Fuel theft percentage, unit %, tracker will send alarm when the fuel level decrement exceeds the setting value. If <u>theft-percentage==0</u> or field empty, disable fuel theft alarm. 04 filling-percentage: Fuel filling percentage, unit %, tracker will send alarm when the fuel level increment exceeds the setting value. If <u>filling-percentage==0</u> or filed empty, disable fuel filling alarm. 05 use-acc: Whether tracker connects to ACC or not. To get better calculation result, it is suggested to connect IN2 to ACC. If <u>use-acc</u> field empty, by default, it is regarded that ACC connected. |
| Reply | B80,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B80,1,5 01 Enable fuel theft alarm calculated based on AD1; When fuel level decrement exceed 5%, tracker sends theft alarm 02 Disable fuel filling alarm 03 IN2 connects to ACC |
| Retrieve | C04,B80 |

B81 – Setting Fuel Level Alarm

| | |
|--------|--------------|
| Source | GPRS/COM/SMS |
|--------|--------------|

| | |
|-------------|---|
| Description | <p>B81,<ad-idx>,<low-percentage>,<high-percentage></p> <p>01 The command is used for AD fuel sensor, such as AS10; Besides, it is valid on regular tank only at present.</p> <p>02 ad-idx: AD channel which connects to fuel sensor, value 1/2; If <u>ad-idx==0</u>, disable fuel level detection.</p> <p>03 low-percentage: Percentage of low fuel level, unit %, tracker will send alarm when the fuel level is lower than the setting value. If <u>low-percentage==0</u> or field empty, disable low fuel level detection.</p> <p>04 high-percentage: Percentage of high fuel level, unit %, tracker will send alarm when the fuel level is higher than the setting value. If <u>high-percentage==0</u> or field empty, disable high fuel level detection.</p> |
| Reply | <p>B81,<err_code></p> <p>01 err_code: procession error code.</p> <p style="padding-left: 40px;">OK – Succeed.</p> <p style="padding-left: 40px;">UNSUPPORT – Command not supported.</p> <p style="padding-left: 40px;">FAILED – Procession failed.</p> |
| Example | <p>B81,1,15,80</p> <p>01 Enable low and high fuel level detection calculated based on AD1</p> <p>02 When fuel level is lower than 15%, tracker sends alarm</p> <p>03 When fuel level is higher than 80%, tracker sends alarm</p> |
| Retrieve | C04,B81 |

B82 – Enable/Disable Fuel Consumption Statistics

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | <p>B82,<ad-idx>,<use-acc>,<add-theft>,<clear></p> <p>01 The command is used for AD fuel sensor, such as AS10; Besides, it is valid on regular tank only at present.</p> <p>02 ad-idx: AD channel which connects to fuel sensor, value 1/2; If <u>ad-idx==0</u>, disable fuel consumption statistics.</p> <p>03 use-acc: Whether tracker connects to ACC or not. To get better calculation result, it is suggested to connect IN2 to ACC. If <u>use-acc</u> field empty, by default, it is regarded that ACC connected.</p> <p>04 add-theft: 1-- The amount of oil reduced by theft is added to total fuel consumption (default); 0-- The amount of oil reduced by theft is excluded from total fuel consumption.</p> <p>05 clear: 0—Keep current fuel consumption data unchanged; 1—Clear current consumption data, and calculated from 0</p> <p>06 After fuel consumption statistics enabled, fuel consumption data is packed in <u>fuel consume</u> field in GPRS protocol.</p> |
| Reply | <p>B82,<err_code></p> <p>01 err_code: procession error code.</p> <p style="padding-left: 40px;">OK – Succeed.</p> |

| | |
|----------|--|
| | <p>UNSUPPORT – Command not supported.</p> <p>FAILED – Proccession failed.</p> |
| Example | <p>B82,1,1,1,1</p> <p>01 Enable fuel consumption statistics calculated based on AD1; tracker connects to ACC via IN2; All amount, including fuel theft amount, will be statistics into total consumption; After commands sent, tracker clear current consumption data, and re-calculates from 0.</p> |
| Retrieve | <p>C04,B82</p> <p>Reply: B82,<ad-idx>,<use-acc>,<add-theft></p> |

B90 – Reset Tracker or Module

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | <p>B90,< select ></p> <p>01 select: option</p> <p style="padding-left: 40px;">=1: Reset tracker.</p> <p style="padding-left: 40px;">=2: Reset GPS module.</p> <p style="padding-left: 40px;">=3: Reset GSM module.</p> |
| Reply | <p>B90,<err_code></p> <p>01 err_code: proccession error code.</p> <p style="padding-left: 40px;">OK – Succeed.</p> <p style="padding-left: 40px;">UNSUPPORT – Command not supported.</p> <p style="padding-left: 40px;">FAILED – Proccession failed.</p> |
| Example | <p>B90,1</p> <p>01 Reset tracker.</p> |
| Retrieve | UNSUPPORT |

B91 – Setting Parameters to Default

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | <p>B91</p> <p>01 After command is set, all system parameters (except SMS password) are set to default.</p> |
| Reply | <p>B91,<err_code></p> <p>01 err_code: proccession error code.</p> <p style="padding-left: 40px;">OK – Succeed.</p> <p style="padding-left: 40px;">UNSUPPORT – Command not supported.</p> <p style="padding-left: 40px;">FAILED – Proccession failed.</p> |
| Example | B91 |
| Retrieve | UNSUPPORT |

B94 – Turn on/off LED Display

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B94,<led-on> 01 led-on: 1--turn on LED, 0--turn off LED. 02 Default, <u>led-on</u> =1. |
| Reply | B94,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B94 01 Set LED to default: turn on. |
| Retrieve | C04,B94 |

B96 – Enable/Disable Vibration Alarm

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | B96,<enable>,<option> 01 enable: 0~Disable vibration alarm(default); 1~enable vibration alarm 02 option: Detection option for vibration alarm <u>option</u> ==1: Trigger alarm when vibration detected and ACC OFF(default) <u>option</u> ==0: Trigger alarm when vibration detected 03 Using <u>B29</u> command to set sensitivity of motion sensor |
| Reply | B96,<err_code> 01 err_code: procession error code. OK – Succeed. UNSUPPORT – Command not supported. FAILED – Procession failed. |
| Example | B96,1 01 Enable vibration alarm |
| Retrieve | C04,B96 |

B99 – OTA using FTP Server

| Source | GPRS/COM/SMS | | | | |
|-------------|--|--------|-------------|------------|--|
| Description | B99,<file_name>,<option>,<ftp_address>,<ftp_port>,<ftp_loginid>,<ftp_loginpwd>,<apn >,<apn_name>,<apn_pwd> 01 file_name: file name for OTA, should be “xxx.bin” format 02 option: option for OTA, when the field empty, using default setting | | | | |
| | <table border="1"> <thead> <tr> <th>option</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0(default)</td> <td>Normal OTA, tracker check whether <u>file_name</u> match current version</td> </tr> </tbody> </table> | option | Description | 0(default) | Normal OTA, tracker check whether <u>file_name</u> match current version |
| option | Description | | | | |
| 0(default) | Normal OTA, tracker check whether <u>file_name</u> match current version | | | | |



| | | | | | |
|----------|---|--|--------|---|---|
| | <table border="1"> <tr> <td></td> <td>or not</td> </tr> <tr> <td>1</td> <td>Mandatory OTA, tracker doesn't check <u>file_name</u></td> </tr> </table> <p>03 ftp_address: FTP server address, default 47.88.17.17 04 ftp_port: FTP server port, default 21 05 ftp_loginid, ftp_loginpwd: FTP login user-name and password, when fields empty, using default account on 47.88.17.17 06 apn, apn_name, apn_pwd: APN setting for FTP connection, default, tracker using the same setting as <u>B01</u> command 07 After <u>B99</u> command received, tracker matches <u>file_name</u> to current firmware version, and starts OTA according to result 08 During OTA operation, tracker will disconnect from tracking server, stop timing uploading. 09 The timeout for FTP OTA is 15mins, when exceed, tracker will restart automatically, and connect to tracking server 10 External power connection is needed during OTA operation, it is used for tracking reboot after OTA finished</p> | | or not | 1 | Mandatory OTA, tracker doesn't check <u>file_name</u> |
| | or not | | | | |
| 1 | Mandatory OTA, tracker doesn't check <u>file_name</u> | | | | |
| Reply | <p>B99,<err_str> 01 err_str: Error code, string format "Invalid BIN file" - <u>file_name</u> doesn't match current firmware version "No ext-pwr, Please Connect in 15mins" – External power disconnect "The Same Version" – file_name has the same version to current firmware version "OK" – OTA start</p> | | | | |
| Example | <p>B99,100-V1.16.bin 01 Start OTA, tracker will connect to 47.88.17.17:21, using default FTP account for file download</p> <p>B99,100-V1.16.bin,1, 120.24.95.123,9208,klone,klone@@2017 01 Start OTA, tracker will connect to <u>120.24.95.123:9208</u>, and upgrade to "<u>100-V1.16.bin</u>" 02 The login name and password of FTP server is "<u>klone</u>" and "<u>klone@@2017</u>"</p> | | | | |
| Retrieve | | | | | |

C01 – Retrieve Position Information

| | |
|-------------|--|
| Source | COM/SMS/GPRS |
| Description | <p>C01 01 After command is set, tracker sends a position message. 02 When alarm detected, tracker sends alarm SMS with <u>C01</u> format automatically, to all SOS number(s). 03 When command is sent via GPRS, tracker replies normal position data.</p> |
| Reply | When command is sent via GPRS, the replied data is normal position package. |

| | |
|----------|--|
| | <p>When command is sent via SMS/COM <string_head>,yyyy-MM-dd hh:mm:ss, <spd>KM/h,<gprs_st>,<gps_fix>,EXPW:<PST> http://maps.google.com/maps?q=<Latitude>,<Longitude>&t=m</p> <p>a string_head: SMS head string, for normal position data, <i>string_head</i> is empty, for alarm data, refer to Appendix-A for default string.</p> <p>b yyyy-MM-dd hh:mm:ss: current date & time, which is effected by B14 command setting.</p> <p>c spd: current speed, unit km/h.</p> <p>d gprs_st: GPRS link status, value: "Connected" or "Disconnected".</p> <p>e gps_fix: GPS signal status, 'A'-fixed, 'V'-not fixed.</p> <p>f PST: Status of ext-power input, "ON" -- ext-power is connected, "OFF" -- ext-power is disconnected.</p> <p>g Latitude, Longitude: Latitude and longitude of last position point.</p> |
| Example | C01 |
| Retrieve | UNSUPPORT |

C02 – Retrieve Firmware/Hardware Version, SN, IMEI

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | C02 |
| Reply | <p>Uploading data format: C02,<IMEI>,<SN>,<fw_ver>,<hw_ver> 01 IMEI: IMEI of tracker. 02 SN: Serial number of tracker. 03 fw_ver: Firmware version. 04 hw_ver: Hardware version.</p> |
| Example | C02 |
| Retrieve | UNSUPPORT |

C03 – Retrieve Supply Power Status

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | C03 |
| Reply | <p>Uploading data format: C03,<extp_v>,<bat_v>,<bat_percentage> 01 extp_v: Voltage of ext-power, unit V. Charge supplier voltage for handheld tracker. 02 bat_v: Voltage of internal battery. 03 bat_percentage: Percentage of internal battery capacity.</p> |
| Example | C03 |
| Retrieve | UNSUPPORT |

C04 – Retrieve Parameter Setting

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | C04,<cmd-code>,<query_para> 01 cmd-code: Command code to be retrieved. 02 query_para: Query parameter; refer to chapters above for detail. |
| Reply | C04,<cmd>,<cmd-para> 01 cmd-code: The same as sending command. 02 cmd-para: Retrieved parameter string, the same format as setting command described in the above chapters. |
| Example | Refer to chapters above. |
| Retrieve | UNSUPPORT |

C06 – Retrieve Basic Information of Tracker

| | |
|-------------|--|
| Source | GPRS/COM/SMS |
| Description | C06 01 Retrieve basic information of tracker in batch 02 The command is commonly used for GPRS linkage lost debug |
| Reply | C06,<GID>,<ip>:<port>,<TCP/UDP>;APN:<apn>,<apn_user>,<apn_pwd>;EXT:<ext_p>,BAT:<bat_v>;B03:<base_int> ,<accoff_int>,<ns_int>;<ACC ON/OFF>,<Moving/STOP> 01 GID: Tracker ID for GPRS data, default IMEI 02 ip, port: Server setting in tracker 03 TCP/UDP: Transport protocol setting, string, value “TCP” / “UDP” 04 apn, apn_user, apn_pwd: APN setting in tracker 05 ext_p: Voltage of external power supply, unit V 06 bat_v: Voltage of internal battery, unit V 07 base_int, accoff_int, ns_int: GPRS uploading interval for normal situation, for ACC OFF, for parking status, which is the same as <u>B03</u> setting 08 ACC ON/OFF: Current ACC status, string, value “ACC ON” / “ACC OFF” 09 Moving/STOP: Current motion status, string, value “Moving” / “STOP” |
| Example | Command: C06 Reply: C06,861694033095389,47.88.35.165:10502,TCP;APN:CMNET,,,;EXT:12.00V,BAT:4.17V;B03:100,0,0,ACC OFF,Stop |
| Retrieve | UNSUPPORT |

C08 – Retrieving AD voltage

| | |
|-------------|---|
| Source | GPRS/COM/SMS |
| Description | C08,<rt-data> 01 The command is used to retrieve voltage on AD port. |



| | |
|----------|---|
| | <p>02 <i>rt-data</i>: 1(default)—Tracker reply real-time voltage; 0—Tracker does smooth filtration, and then replies</p> <p>03 Different for <i>rt-data</i></p> <p><i>rt-data==1</i>: Voltage is related to sensor itself, when sensor signal is stable, sending C08 command for retrieving, and the result would be true</p> <p><i>rt-data==0</i>: Voltage is related not only to sensor itself, but to working environment (e.g. fuel sensor voltage on running vehicle). Tracker needs at least 1min to sample enough data, does smooth filtration. There could have some error to true voltage.</p> <p>04 The result of <u>C08</u> reply is actual voltage on AD port, which isn't effected by <u>B34</u> command setting</p> |
| Reply | <p>C08,<AD1>:<ad1-voltage></p> <p>01 ad1-voltage: Voltage on AD1, unit V</p> |
| Example | <p>Command: C08</p> <p>Reply: C08,AD1:4.32</p> |
| Retrieve | UNSUPPORT |

Appendix A – Alarm code and alarm parameter

The following table describes the relationship of *alm-code* and *alm-para* in GPS Position/Alarm data:

| alm-code | alm-para | Description | SMS Head String |
|----------|--|-----------------------|------------------|
| 1 | NULL | Distance tracking | Distance |
| 2 | NULL | Input1 active | SOS |
| 3 | NULL | Input1 inactive | IN1 Inactive |
| 4 | NULL | Input2 active | IN2 |
| 5 | NULL | Input2 inactive | IN2 Inactive |
| 6 | NULL | Input3 active | IN3 |
| 7 | NULL | Input3 inactive | IN3 Inactive |
| 14 | Ext-power voltage, unit V | Ext-power low | Low Ext-Power |
| 15 | NULL | Ext-power lost | Ext-Power Cut |
| 16 | NULL | Ext-power re-connect | Ext-Power On |
| 17 | Battery voltage, unit V | Internal battery low | Low Battery |
| 18 | NULL | Speeding alarm | Speeding |
| 21 | NULL | Vibration Alarm | Vibration |
| 20 | NULL | GPS antenna cut | GPS Antenna Cut |
| 23 | NULL | Harsh accelerate | Harsh Accelerate |
| 24 | NULL | Harsh braking | Harsh Braking |
| 27 | NULL | Fatigue driving | Fatigue Driving |
| 28 | NULL | Fatigue relieve | Fatigue Relieve |
| 29 | NULL | Parking overtime | Parking Overtime |
| 30 | NULL | GSM Jamming | GSM Jamming |
| 32 | NULL | GPS jamming | GPS Jamming |
| 33 | Hexadecimal character: bit[7:4]: geo-fence type: 0 - Circle fence 1 - Polygon fence bit[3:0]: index of fence | Exit geo-fence | Exit Fence |
| 34 | The same as "Exit geo-fence" | Enter geo-fence | Enter Fence |
| 35 | NULL | Idling Alarm | Idling Alarm |
| 44 | NULL | Fuel Theft Alarm | Fuel Theft |
| 45 | NULL | Fuel Filling Alarm | Fuel Filling |
| 46 | NULL | Low Fuel Level Alarm | Fuel Level Low |
| 47 | NULL | High Fuel Level Alarm | Fuel Level High |